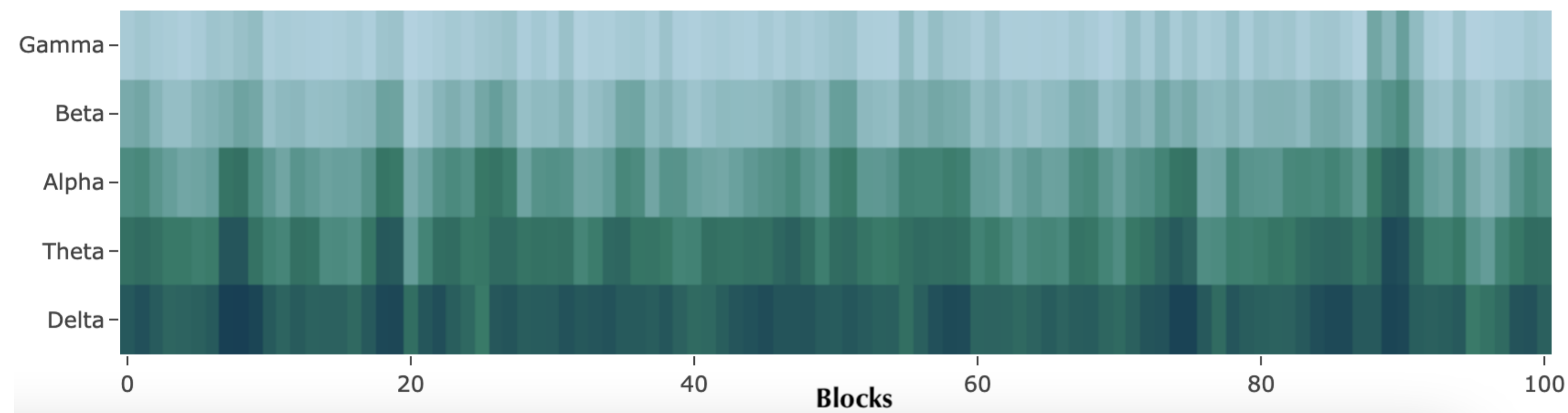


## Background

- Increase in the power of **high frequencies** has been found in brain signals during the onset of an epileptic seizure.
- **Hypothesis:** By analyzing the tail of the brain energy distribution during high-frequency oscillations, we can reveal key channels that could **trigger bursts of electrical activity** in brain signals.
- Key channels that induce seizures may only reveal themselves during the **burst-phase**.
- **Contributions:** (a) metric for the comparison of tail associations of bursts for ictal and non-ictal neonates; and (b) reveal key channels in brain connectivity of patients at risk of epilepsy.

## Time-Frequency Analysis for Non-stationary Series



### Time-Varying Periodogram:

- $X(t)$  is a locally stationary time series
- At time block  $b$  of length  $M$ , compute the local periodogram:

$$I(b, \omega_k) = \frac{1}{M} \left| \sum_{t \in b} X(t) \exp(-i2\pi\omega_k t) \right|^2$$

where  $\omega_k = k / (\text{SR} \times \text{seconds})$

- Compute the periodograms at the frequency bands delta (0 - 4 Hertz (Hz)), theta (4 - 8 Hz), alpha (8 - 12 Hz), beta (12 - 30 Hz), and gamma (30 - 50 Hz). The periodogram at band  $\Omega$  is equation  $I(b, \Omega) = 1 / \|\Omega\| \sum_{\omega_k \in \Omega} I(b, \omega_k)$ .

**Spectral Clustering** can be used for quicker detection of burst and suppression phase in EEG [2]. Consider the similarity measure of blocks contained in matrix  $S$  such that  $S_{b,b'}$  is

the similarity between two blocks  $b$  and  $b'$ , given as:  $S_{b,b'} = \exp\left(-\frac{\|(\Sigma(h=0,b), \Sigma(h=0,b'))\|_F^2}{2\gamma}\right)$ ,

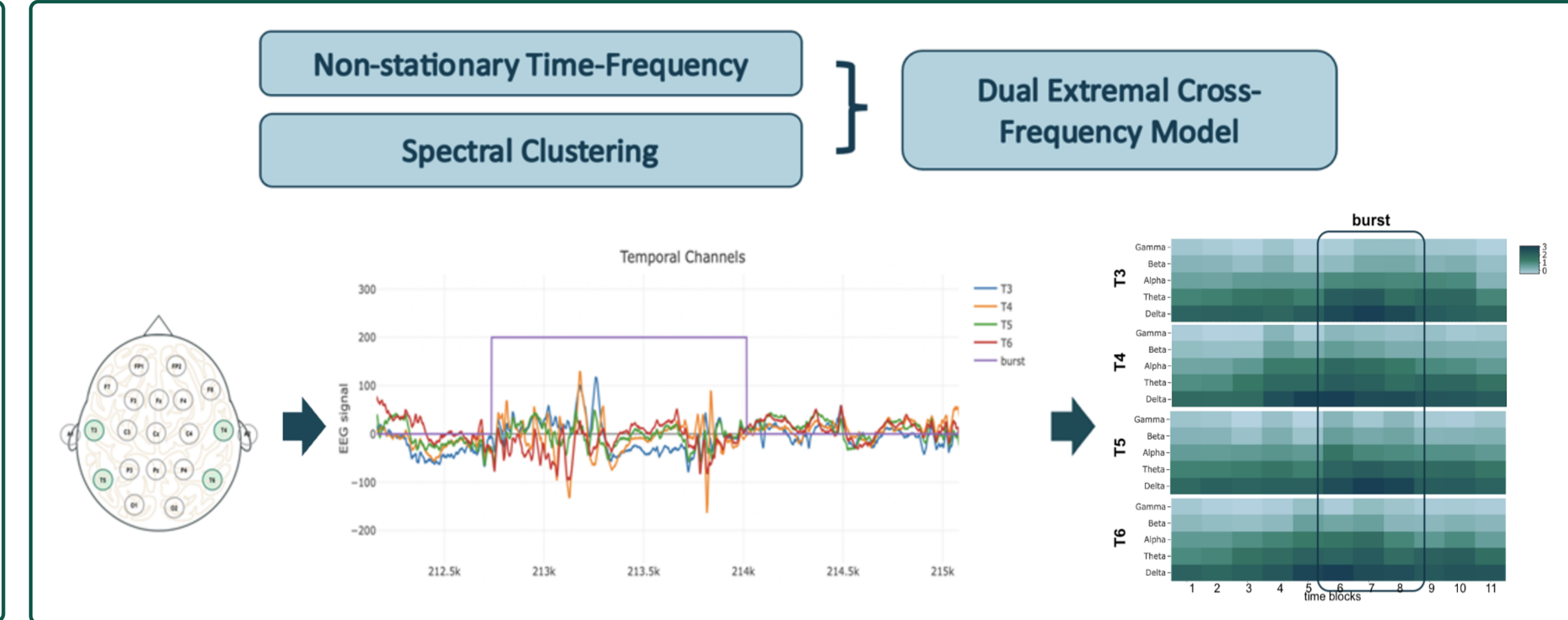
- Let  $L = D - S$ , where  $D = \text{diag}\{d_1, d_2, \dots, d_{B=1000}\}$  and  $d_i$  is the degree of a vertex  $v_b = \sum_{i=b}^B S_{b,i}$ . The clustering is done by performing k-means on eigenvectors of  $Lu = \lambda Du$ .

## Framework

Consider four channels at the temporal lobe namely T3, ..., T6 indexed by  $p = 1, \dots, 4$ . **DEC Model** is defined for  $I_d(b, \omega) := (I_{1,d}(b, \omega), \dots, I_{4,d}(b, \omega))'$ . Denote by  $I_{-p,d}(b, \omega)$  the vector  $I_d(b, \omega)$  with its  $p^{\text{th}}$  component removed;  $d = 1$  and  $d = 2$  correspond to burst and non-burst phases. Then, for all  $u_{p,d} > v_{p,d}$  for some high threshold  $v_{p,d} > 0$ , the [1] model asserts that

$$\left( I_{-p,d}(b, \omega) \mid I_{p,d}(b, \omega) = u_{p,d} \right) = \phi_{-p,d} I_{p,d}(b, \omega) + I_{p,d}(b, \omega) \psi_{-p,d} Z_{-p,d}(b, \omega), \quad (1)$$

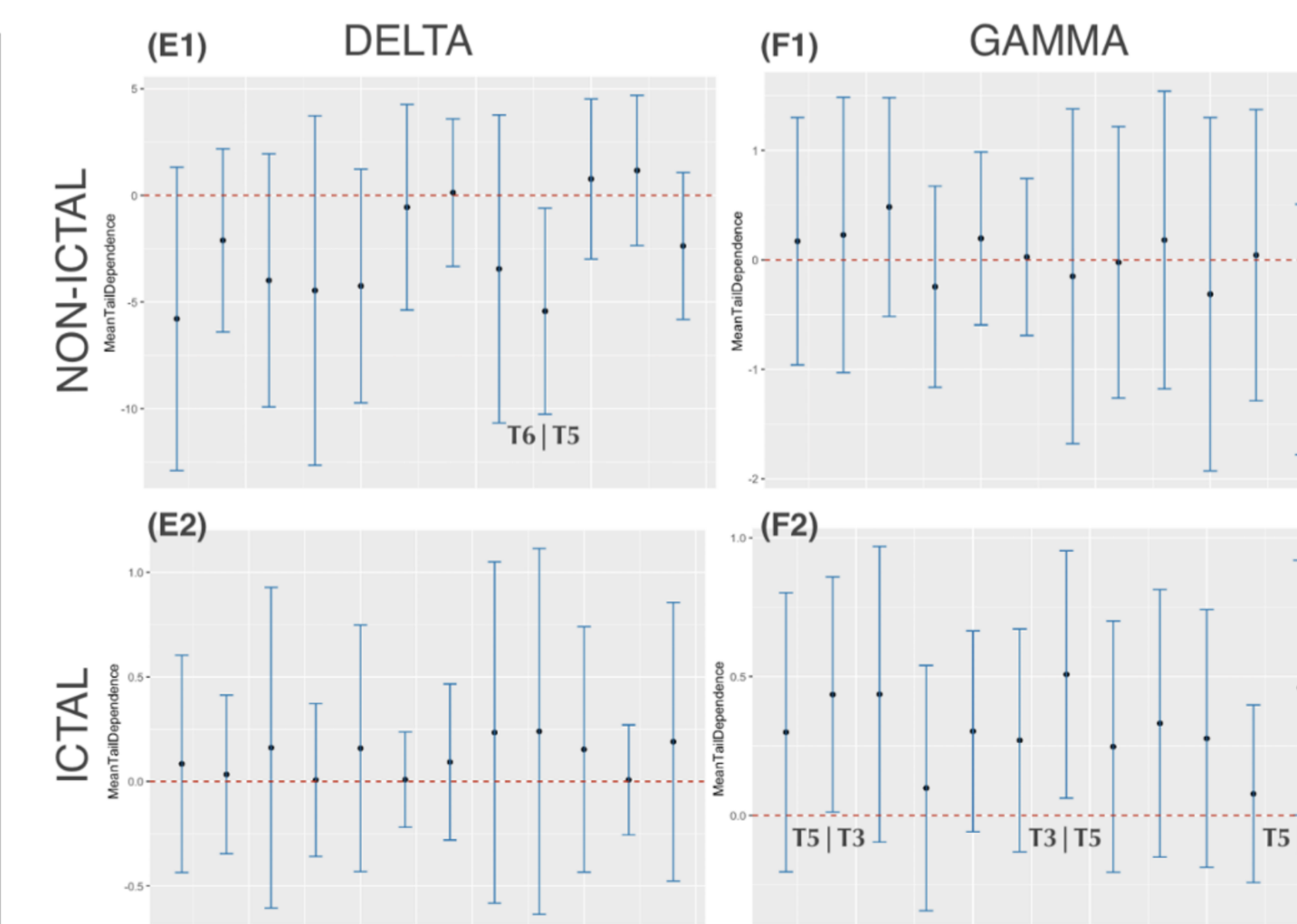
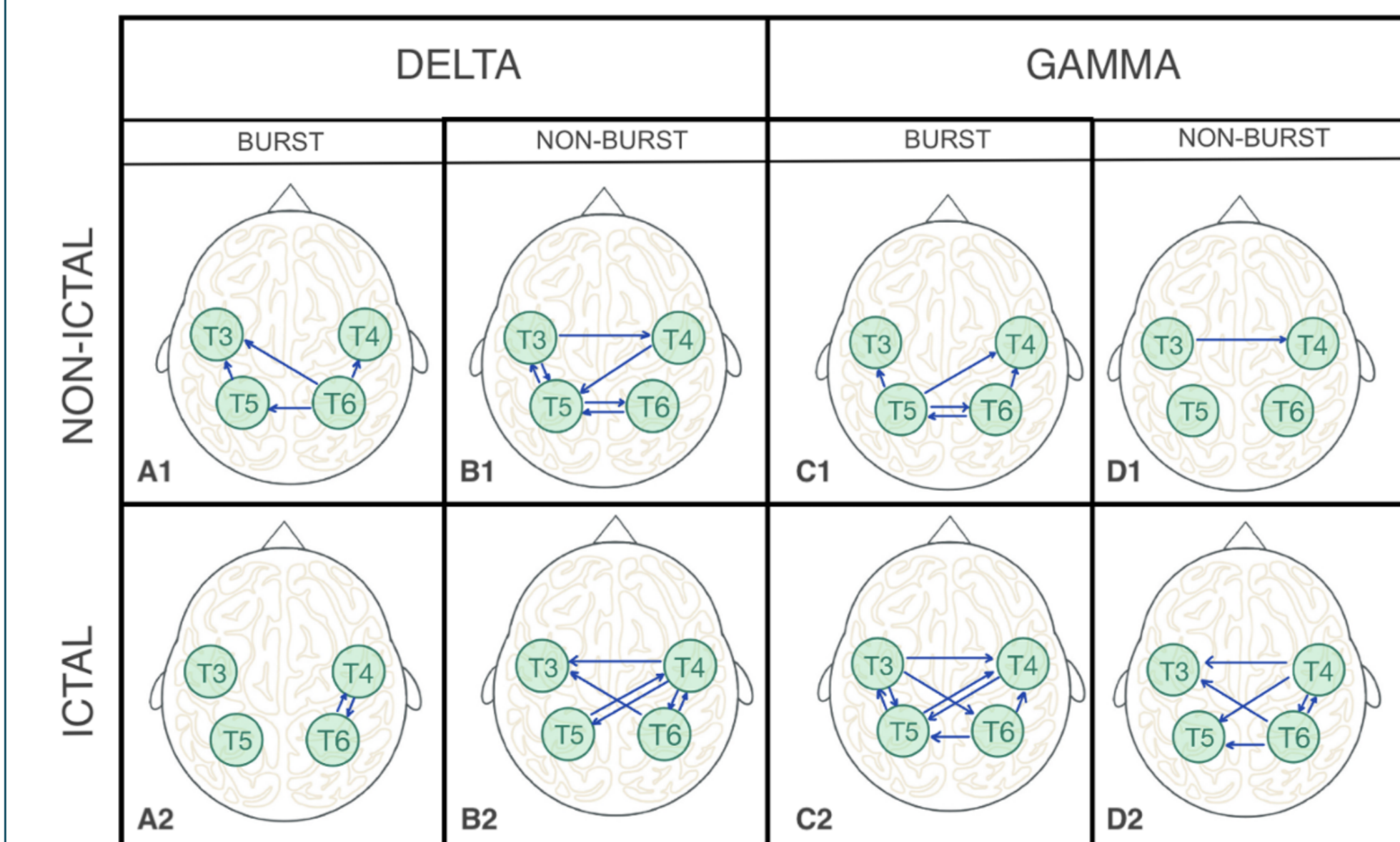
with parameter vectors  $\phi_{-p,d} \in [-1, 1]^3$  and  $\psi_{-p,d} \in (-\infty, 1)^3$  dependent on channel  $p$  and phase-type  $d \in \{1, 2\}$ .  $Z_{-p,d}(b, \omega) \sim \text{MVN}(\mu_{-p,d}, \Sigma_{-p,d})$  for mean vector and covariance matrix  $\mu_{-p,d}$  and  $\Sigma_{-p,d}$ , respectively.



- **Conditional expectation** combines information from both  $\phi_{-p,d}$  and  $\psi_{-p,d}$ :  $m_{p,q;d}(\omega) = \hat{E}[I_{q,d}(b, \omega) \mid I_{p,d}(b, \omega) = u_{p,d}] = \hat{\phi}_{-p,q;d} u_{p,d} + u_{p,d}^{\hat{\psi}_{-p,q;d}} \hat{\mu}_{-p,q;d}$ ;  $p \neq q$ , [3]
- **Bootstrap:** We used a non-parametric bootstrap to estimate parameter uncertainty of the DEC model. For each clusters, we resampled the blocks then re-fitted the DEC model to each resamples to obtain bootstrap estimates for  $\phi_{p,q;d}$  and conditional mean difference (i.e.,  $m_{diff} = m_{p,q;1} - m_{p,q;2}$ ) for all pairwise combination of channels.

## Subject Level Results and Future Work

### Subject Level Analysis:



### Future Work:

- **Multi-subject DEC;** utilize Extreme Vector Autoregressive Model with subject-specific effects:  $\left( I_{-i}^{(s)}(b, \omega) \mid I_i^{(s)}(b, \omega) = u_i^{(s)} \right) = F^{(s)}(b, \omega) + D^{(s)}(b, \omega)$ ; for all  $u_i^{(s)} > v_i^{(s)}$ .
- $F^{(s)}(b, \omega)$  is the subject-specific fixed-effects, while  $D^{(s)}(b, \omega)$  has the subject-specific tail connectivity matrices of four clusters. We will use  $D$  to represent the **DEC model**.
- The simplest case of  $D^{(s)}(b+h, \omega) = D_{\omega}^{(s)}(b+h)$  is for lag 1 fixing  $\Psi = 0$  which is given by:

$$D_{\omega}^{(s)}(b) = [\Phi_{1,1}^{(s)} E_{1,b}^{(s)} + \Phi_{2,1}^{(s)} E_{2,b}^{(s)}] D_{\omega}^{(s)}(b-1) + e^{(s)}(b)$$

where  $E_{c,b}^{(s)} = E_c^{(s)}(b, \omega)$  is 1 when the block is in extreme set of cluster  $c$  and 0 otherwise. The term  $e^{(s)}(b)$  is a zero-mean white noise multivariate process.

## References

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- [2] Narula, G., Haerberlin, M., Balsiger, J., Strässle, C., Imbach, L.L., and Keller, E.: *Detection of EEG burst-suppression in neurocritical care patients using an unsupervised machine learning algorithm* Clinical Neurophysiology 132, no.10 (2021): 2485-2492.
- [3] Richards, J. and Wadsworth, J.L.: *Spatial deformation for nonstationary extremal dependence* Environmetrics 32, no.5 (2021): e2671.